

Tool for engineering simulations of various unmanned aerial vehicle configurations to optimize parameters and test new concept.

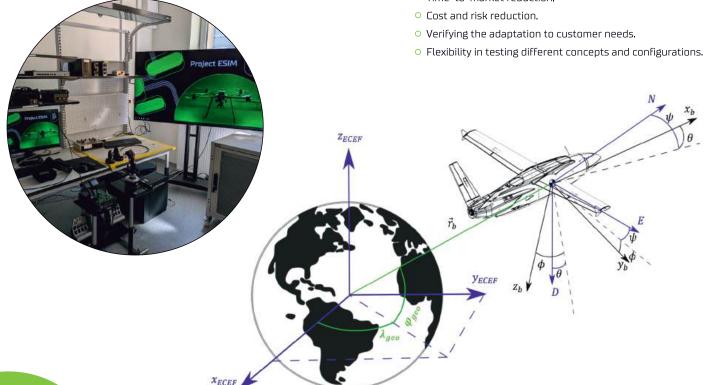
CHARACTERISTICS

- Modeling: Digital Twin of the UAV and the environment with interactive elements.
- Simulation modes: HIL (Hardware In the Loop) and SIL (Software In the Loop).
- Testing UAV in configurations with different types of propulsion.
- $\,\circ\,$ Testing UAV with different types of payloads, e.g., cameras, sensors, cargo.
- Performance analysis of UAVs in different structural configurations and varying takeoff weights.
- Energy consumption analysis.
- Creating virtual UAV missions in selected atmospheric conditions.
- Flight stability assessment.
- Analysis and development of navigation systems, control systems, and mission management algorithms.
- Test flights on a virtual UAV model,



COMPETITIVE ADVANTAGES

- Early-stage problem identification.
- UAV technology optimization.
- O Time-to-market reduction.





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